



Thermistor Temperature Sensors with Python

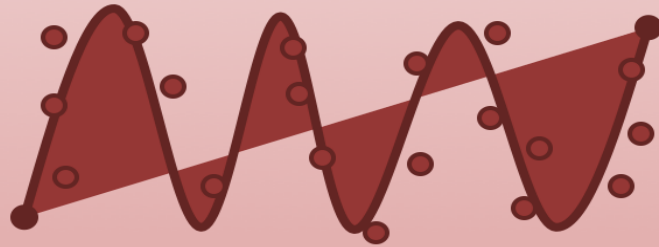
Exemplified by using NI USB-6008 I/O Module

Hans-Petter Halvorsen

Free Textbook with lots of Practical Examples

Python for Science and Engineering

Hans-Petter Halvorsen



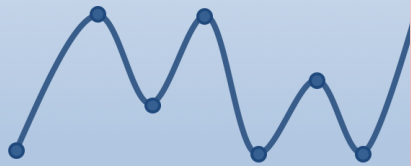
<https://www.halvorsen.blog>

<https://www.halvorsen.blog/documents/programming/python/>

Additional Python Resources

Python Programming

Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Science and Engineering

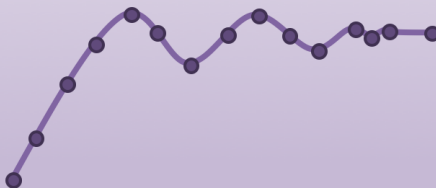
Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Control Engineering

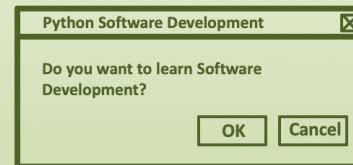
Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Software Development

Hans-Petter Halvorsen



<https://www.halvorsen.blog>

<https://www.halvorsen.blog/documents/programming/python/>

Contents

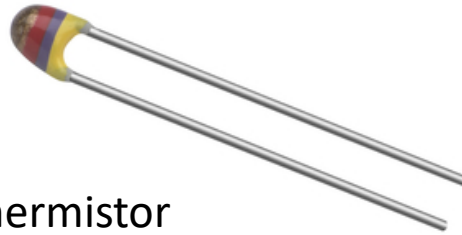
- DAQ and I/O Modules
- NI-DAQ
- Thermistors
 - Resistance Temperature Detectors (RTD)
- Python Examples

Note! The Python Examples provided will work for all NI-DAQ Devices using the NI-DAQmx Driver, which is several hundreds different types. We will use the NI USB-6008 DAQ Device or I/O Module as an Example

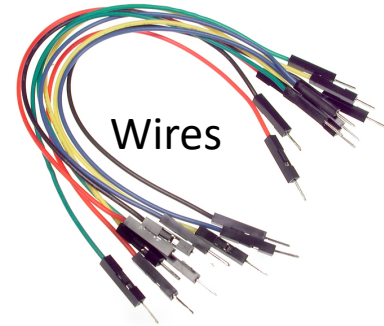
Equipment



USB-6008 (or similar DAQ Device)

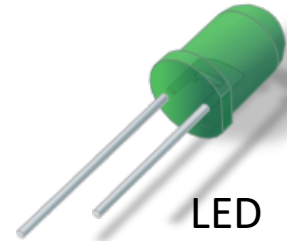
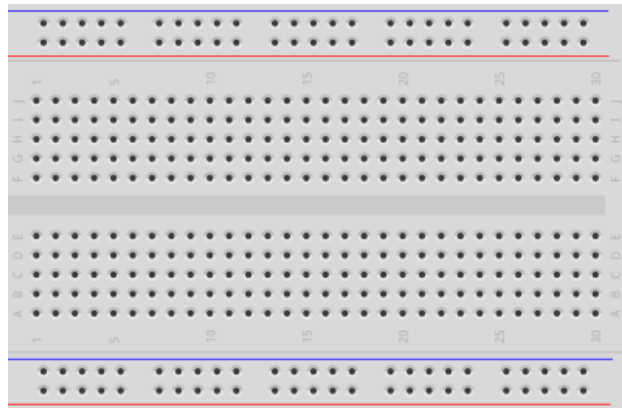


Thermistor

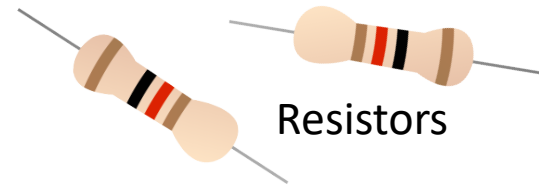


Wires

Breadboard



LED



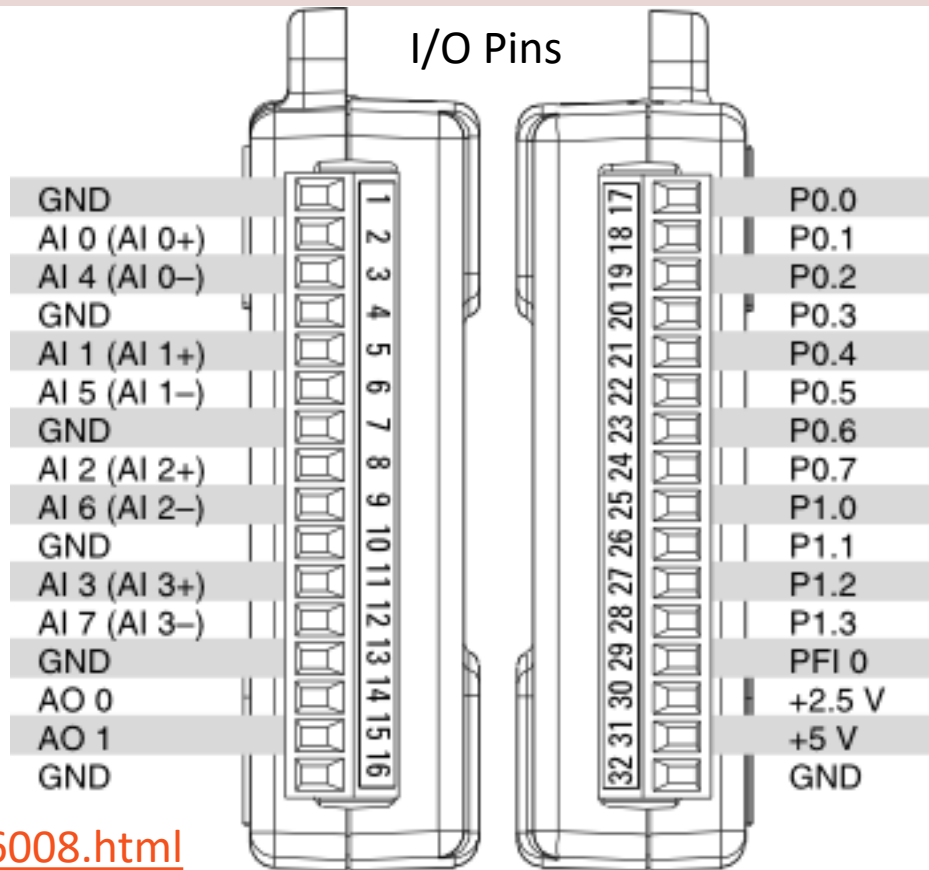
Resistors

NI USB-6008

We will use NI USB-6008 in our examples



I/O Pins



<http://www.ni.com/en-no/support/model.usb-6008.html>

NI DAQ Device with Python

How to use a NI DAQ Device with Python

Python Application

Your Python Program

nidaqmx Python Package

Free

Python Library/API for Communication with NI DAQmx Driver

Python

Free

Python Programming Language

NI DAQmx

Free

Hardware Driver Software

NI DAQ
Hardware

In this Tutorial we will use USB-6008 DAQ Device or I/O Module

DAQ System

Input/Output Signals



Analog Signals



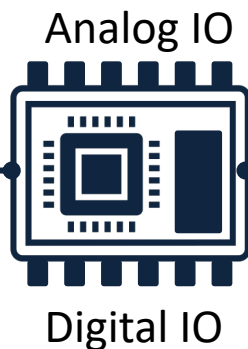
Digital Signals

Sensors



(Analog/Digital Interface)

Data Acquisition Hardware



USB, etc.



PC

Software



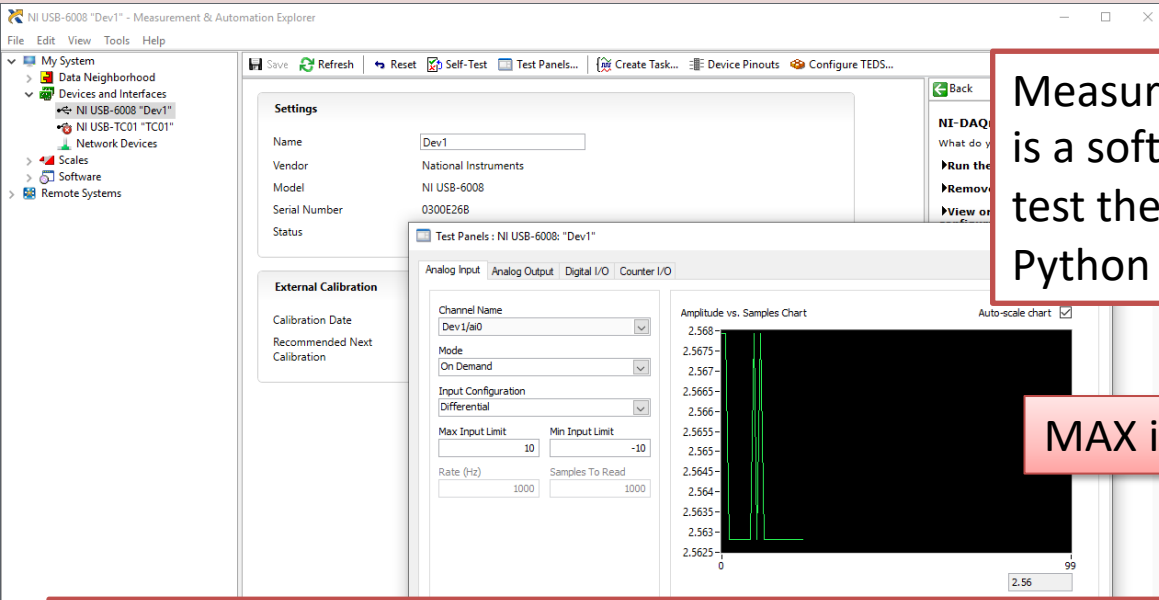
Application

Hardware Driver

NI-DAQmx

- NI-DAQmx is the software you use to communicate with and control your NI data acquisition (DAQ) device.
- NI-DAQmx supports only the **Windows** operating system.
- Typically you use LabVIEW in combination with NI DAQ Hardware, but the NI-DAQmx can also be used from C, C#, Python, etc.
- The NI-DAQmx Driver is Free!
- Visit the ni.com/downloads to download the latest version of NI-DAQmx

Measurement & Automation Explorer (MAX)



Measurement & Automation Explorer (MAX) is a software you can use to configure and test the DAQ device before you use it in Python (or other programming languages).

MAX is included with NI-DAQmx software

With MAX you can make sure your DAQ device works as expected before you start using it in your Python program. You can use the Test Panels to test your analog and digital inputs and outputs channels.

nidaqmx Python API

- Python Library/API for Communication with NI DAQmx Driver
- Running **nidaqmx** requires NI-DAQmx or NI-DAQmx Runtime
- Visit the ni.com/downloads to download the latest version of NI-DAQmx
- nidaqmx can be installed with **pip**:
`pip install nidaqmx`
- <https://github.com/ni/nidaqmx-python>

nidaqmx Python Package

Installation

```
Anaconda Prompt
(base) C:\Users\hansha>pip install nidaqmx
```

```
Anaconda Prompt
(base) C:\Users\hansha>pip install nidaqmx
Collecting nidaqmx
  Using cached https://files.pythonhosted.org/packages/c5/00/40a4ab636f91b6b3bc77e4947ffdf9ad8b4c01c1cc701b5fc6e4df30fe34/nidaqmx-0.5.7-py2.py3-none-any.whl
Requirement already satisfied: six in c:\programdata\anaconda3\lib\site-packages (from nidaqmx) (1.11.0)
Requirement already satisfied: numpy in c:\programdata\anaconda3\lib\site-packages (from nidaqmx) (1.14.3)
distributed 1.21.8 requires msgpack, which is not installed.
Installing collected packages: nidaqmx
Successfully installed nidaqmx-0.5.7
You are using pip version 10.0.1, however version 20.2.3 is available.
You should consider upgrading via the 'python -m pip install --upgrade pip' command.
(base) C:\Users\hansha>
```

<https://www.halvorsen.blog>

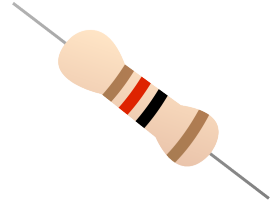
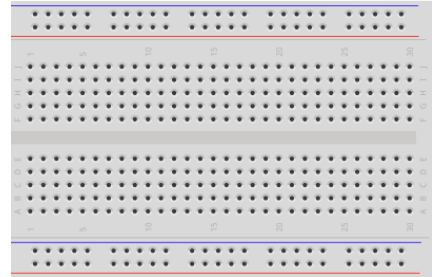
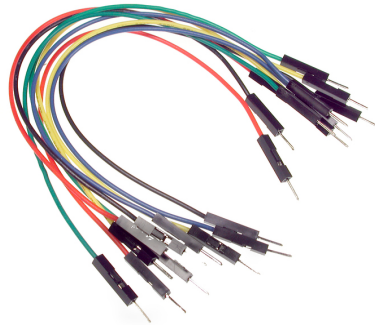


Thermistor with Python

Hans-Petter Halvorsen

Necessary Equipment

- PC
- DAQ Module, e.g., USB-6008
- Breadboard
- Thermistor
- Resistor 10 k Ω
- Wires (Jumper Wires)



Thermistor



A thermistor is an electronic component that changes resistance to temperature - so-called Resistance Temperature Detectors (RTD). It is often used as a temperature sensor.



Our Thermistor is a so-called NTC (Negative Temperature Coefficient). In a NTC Thermistor, resistance decreases as the temperature rises.

There is a **non-linear relationship** between resistance and excitement. To find the temperature we can use the following equation (**Steinhart-Hart equation**):

$$\frac{1}{T} = A + B \ln(R) + C (\ln(R))^3$$

where A, B, C are constants given below [Wikipedia]

$A = 0.001129148, B = 0.000234125$ and $C = 8.76741E - 08$

Steinhart-Hart Equation

To find the Temperature we can use Steinhart-Hart Equation:

$$\frac{1}{T_K} = A + B \ln(R) + C (\ln(R))^3$$

This gives:

$$T_K = \frac{1}{A + B \ln(R) + C (\ln(R))^3}$$

Where the Temperature T_K is in Kelvin

A, B and C are constants

$$A = 0.001129148,$$

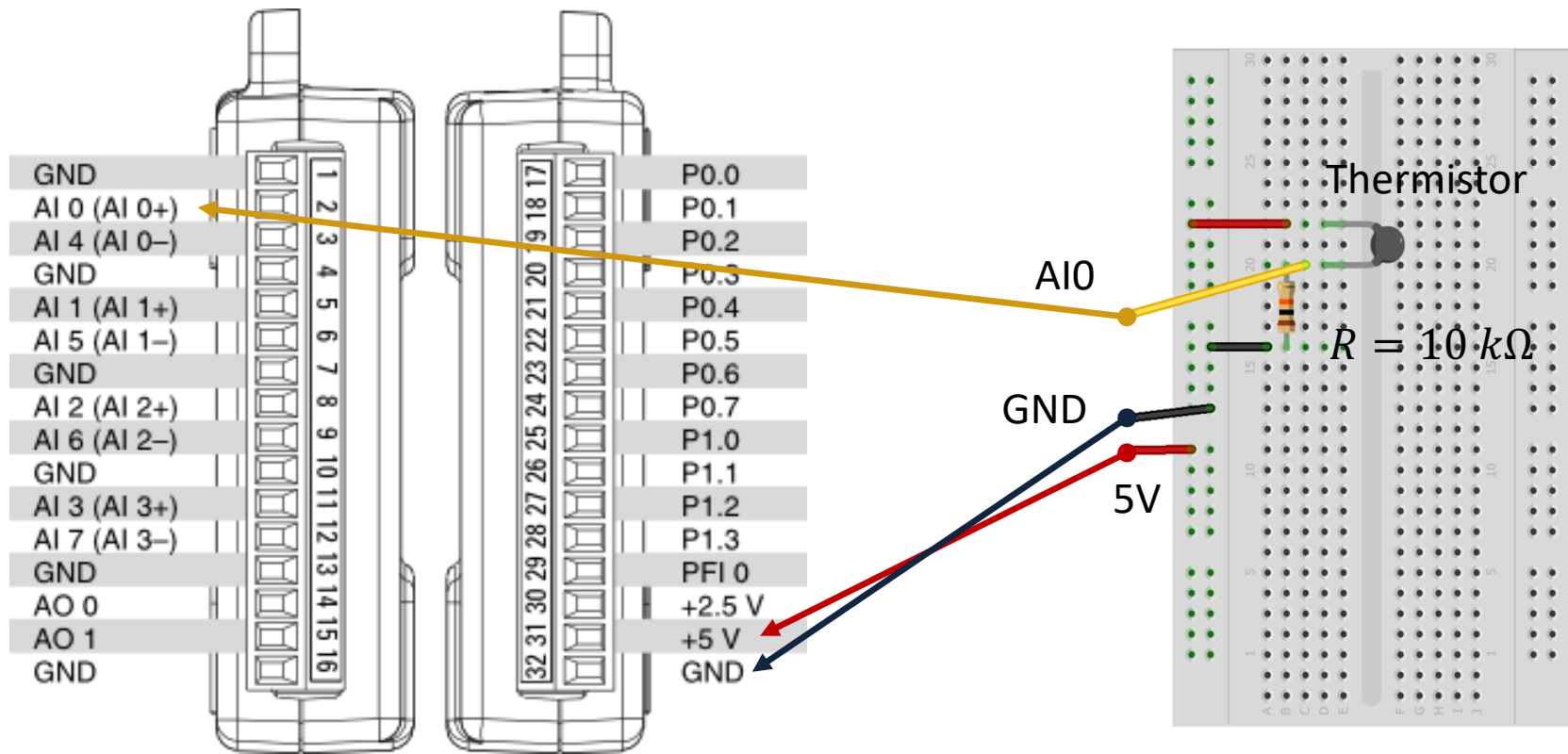
$$B = 0.000234125$$

$$C = 0.0000000876741$$

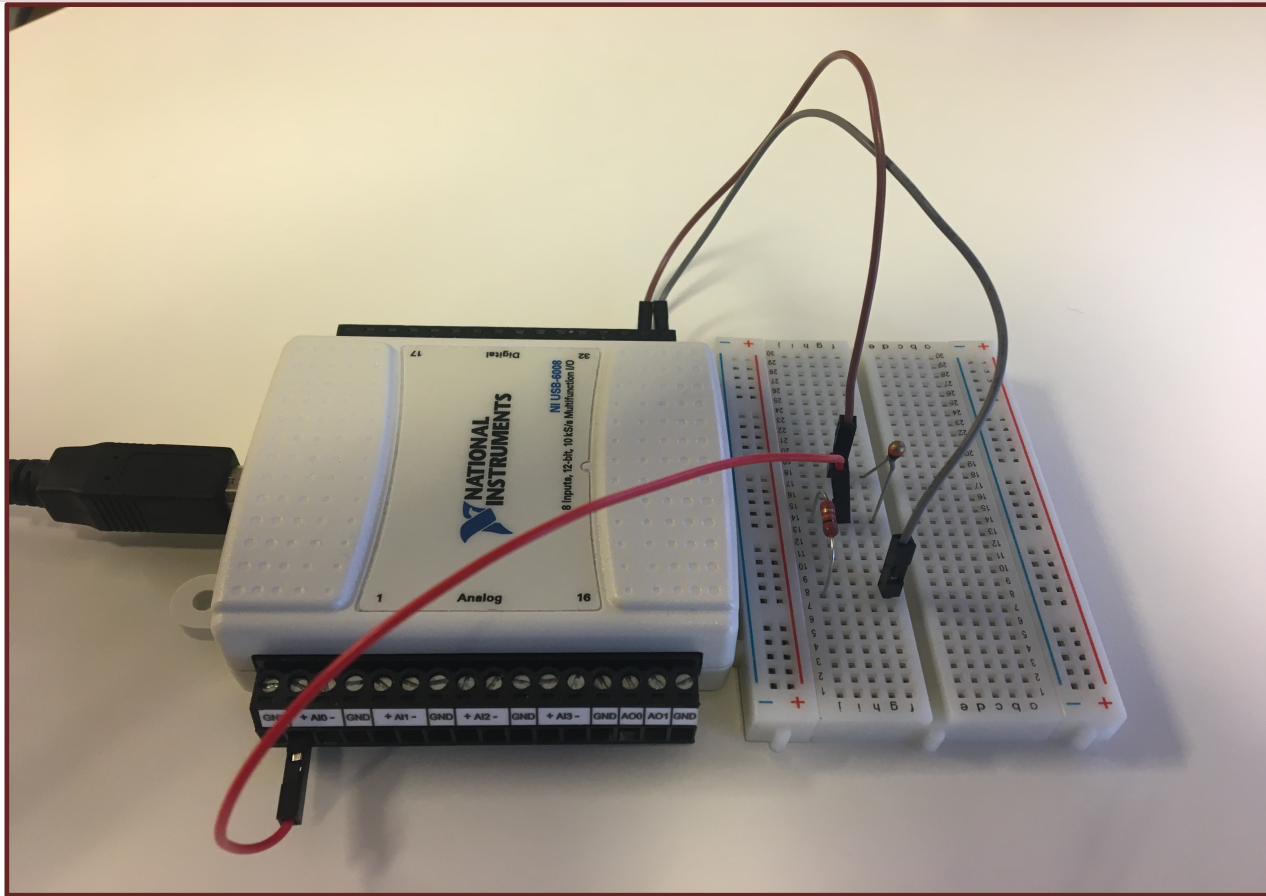
The Temperature in degrees Celsius will then be:

$$T_C = T_K - 273.15$$

Wiring

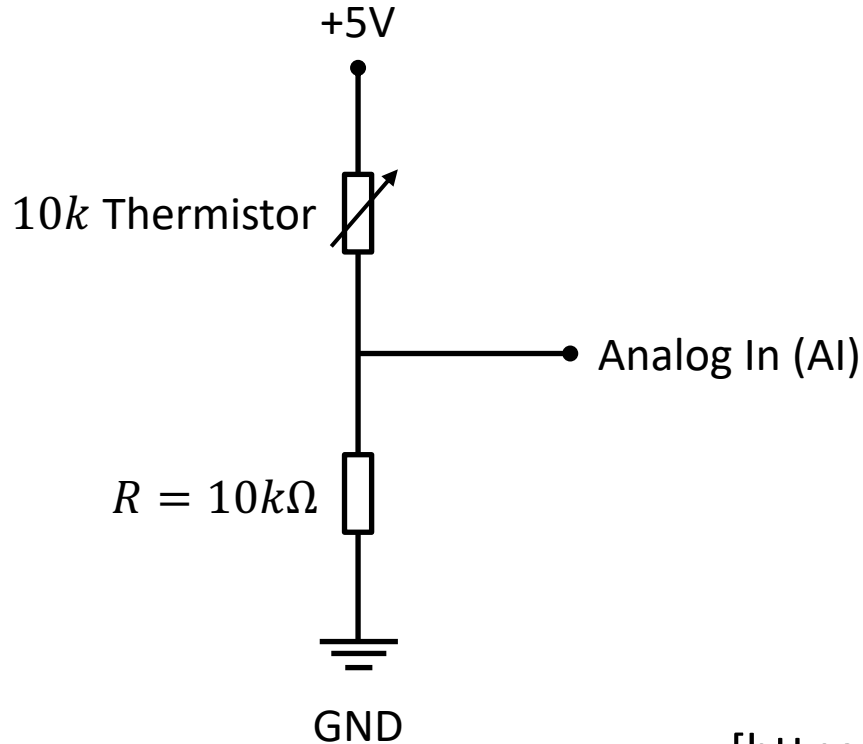


Hardware Setup



Voltage Divider

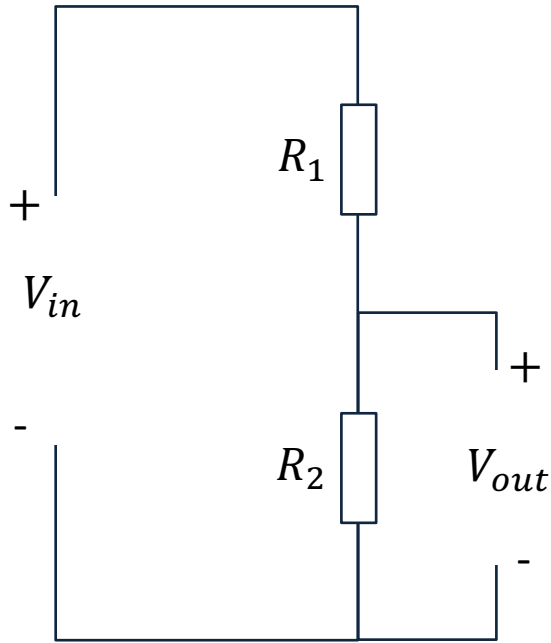
The wiring is called a “Voltage Divider”



[https://en.wikipedia.org/wiki/Voltage_divider]

General Voltage Divider

We want to find V_{out}



Formula:

$$V_{out} = V_{in} \frac{R_2}{R_1 + R_2}$$

Voltage Divider for our System

Voltage Divider Equation:

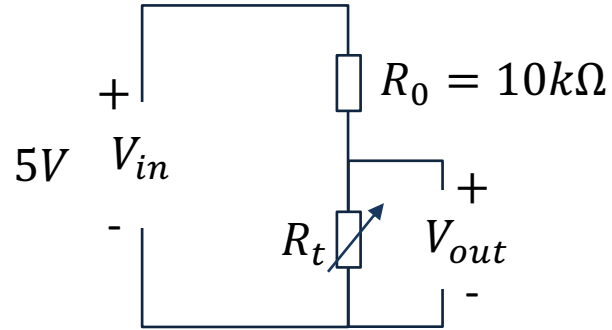
$$V_{out} = V_{in} \frac{R_t}{R_0 + R_t}$$

We want to find R_t :

$$R_t = \frac{V_{out}R_0}{V_{in} - V_{out}}$$

Steps:

1. We wire the circuit on the Breadboard and connect it to the DAQ device
2. We measure V_{out} using the DAQ device
3. We calculate R_t using the Voltage Divider equation
4. Finally, we use Steinhart-Hart equation for finding the Temperature



R_t - 10k Thermistor. This varies with temperature. From Datasheet we know that $R_t = 10k\Omega @ 25^\circ\text{C}$

Python Code

The Code works as follows:

1. Get V_{out} from the DAQ device

2. Calculate $R_t = \frac{V_{out}R_0}{V_{in}-V_{out}}$

3. Calculate $T_K = \frac{1}{A+B \ln(R_t)+C(\ln(R_t))^3}$

4. Calculate $T_C = T_K - 273.15$

5. Present T_C in the User Interface

```
import math as mt
import nidaqmx

# Initialization

from nidaqmx.constants import (
    TerminalConfiguration)

# Voltage Divider
Vin = 5;
Ro = 10000 # 10k Resistor

# Steinhart Constants
A = 0.001129148
B = 0.000234125
C = 0.0000000876741

# Initialize DAQ Device
task = nidaqmx.Task()
task.ai_channels.add_ai_voltage_chan("Dev1/ai0",
                                     terminal_config=TerminalConfiguration.RSE)

task.start()

# Read from DAQ Device
Vout = task.read()
print(Vout)

# Calculate Resistance
Rt = (Vout * Ro) / (Vin - Vout)
#Rt = 10000 # Used for Testing. Setting Rt=10k should give TempC=25

# Steinhart - Hart Equation
TempK = 1 / (A + (B * mt.log(Rt)) + C * mt.pow(mt.log(Rt),3))

# Convert from Kelvin to Celsius
TempC = TempK - 273.15

print(TempC)

task.stop
task.close()
```

Python Code

Here, I have made a separate Python function for the thermistor logic. This makes it easy to use this part in several Applications.

thermistor.py

```
import math as mt

# Function for finding Temperature in degrees Celsius
def thermistorTemp(Vout):
    # Voltage Divider
    Vin = 5;
    Ro = 10000 # 10k Resistor

    # Steinhart Constants
    A = 0.001129148
    B = 0.000234125
    C = 0.0000000876741

    # Calculate Resistance
    Rt = (Vout * Ro) / (Vin - Vout)
    #Rt = 10000 # Used for Testing. Setting Rt=10k should give TempC=25

    # Steinhart - Hart Equation
    TempK = 1 / (A + (B * mt.log(Rt)) + C * mt.pow(mt.log(Rt),3))

    # Convert from Kelvin to Celsius
    TempC = TempK - 273.15

    return TempC
```

Thermistor Application:

```
import time
import nidaqmx
import thermistor

# Initialize DAQ Device
from nidaqmx.constants import (
    TerminalConfiguration)

task = nidaqmx.Task()
task.ai_channels.add_ai_voltage_chan("Dev1/ai0",
    terminal_config=TerminalConfiguration.RSE)
task.start()

# Initialization
Tstop = 60 # Logging Time [seconds]
Ts = 2 # Sampling Time [seconds]
N = int(Tstop/Ts)

for k in range(N):
    # Read from DAQ Device
    Vout = task.read()

    TempC = thermistor.thermistorTemp(Vout)
    print(round(TempC,1))

    time.sleep(Ts)

task.stop
task.close()
```

<https://www.halvorsen.blog>

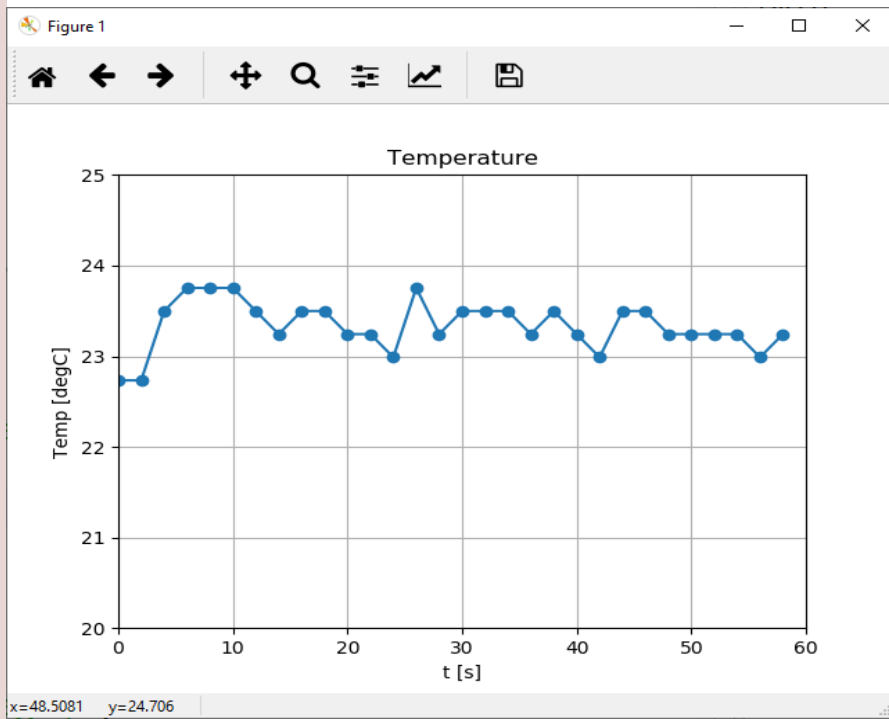


Plotting

Hans-Petter Halvorsen

Plotting Temperature Data

In this Example we read data from the sensor within a For Loop and Plot the Data using matplotlib



```
import numpy as np
import time
import matplotlib.pyplot as plt
import nidaqmx
import thermistor

# Initialize DAQ Device
from nidaqmx.constants import (
    TerminalConfiguration)

# Initialize Logging
Tstop = 20 # Logging Time [seconds]
Ts = 2 # Sampling Time [seconds]
N = int(Tstop/Ts)
data = [] # Create Array for storing Temperature Data

# Initialize DAQ Device
task = nidaqmx.Task()
task.ai_channels.add_ai_voltage_chan("Dev1/ai0",
                                     terminal_config=TerminalConfiguration.RSE)
task.start()

# Start Logging
for k in range(N):
    Vout = task.read()
    TempC = thermistor.thermistorTemp(Vout)
    print(round(TempC,1))
    data.append(TempC)
    time.sleep(Ts)

# Terminate DAQ Device
task.stop
task.close()

# Plotting
t = np.arange(0,Tstop,Ts)
plt.plot(t,data, "-o")
plt.title('Temperature')
plt.xlabel('t [s]')
plt.ylabel('Temp [degC]')
plt.grid()
Tmin = 20; Tmax = 30
plt.axis([0, Tstop, Tmin, Tmax])
plt.show()
```

<https://www.halvorsen.blog>

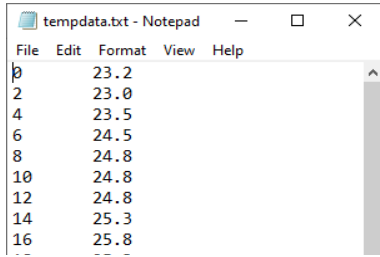


Logging to File

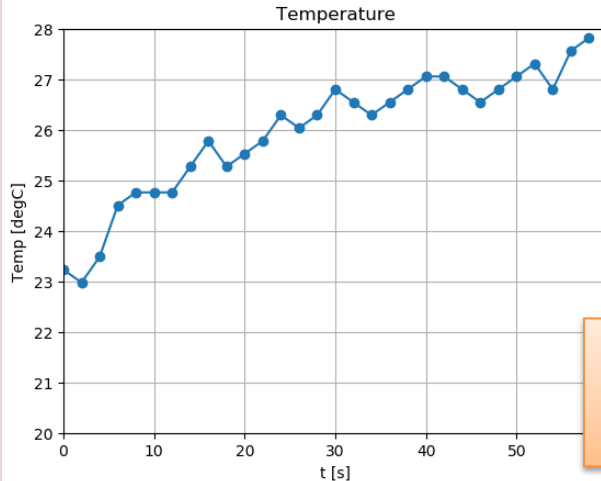
Hans-Petter Halvorsen

Logging Data to File

In this Example we read data from the sensor within a For Loop and Plot the Data using matplotlib and Save the Temperature values to a File as well.



Time [s]	Temperature [degC]
0	23.2
2	23.0
4	23.5
6	24.5
8	24.8
10	24.8
12	24.8
14	25.3
16	25.8
--	--



datalogging.py

```
# Write Data to File Function
def writefiledata(file, t, x):
    time = str(t)
    value = str(round(x, 2))
    file.write(time + "\t" + value)
    file.write("\n")
```

```
import numpy as np
import time
import matplotlib.pyplot as plt
import nidaqmx
import thermistor
import datalogging

# Initialize DAQ Device
from nidaqmx.constants import (
    TerminalConfiguration)

# Open File
file = open("tempdata.txt", "w")

# Initialize Logging
Tstop = 20 # Logging Time [seconds]
Ts = 2 # Sampling Time [seconds]
N = int(Tstop/Ts)
data = [] # Create Array for storing Temperature Data

# Initialize DAQ Device
task = nidaqmx.Task()
task.ai_channels.add_ai_voltage_chan("Dev1/ai0",
    terminal_config=TerminalConfiguration.RSE)
task.start()

# Start Logging
for k in range(N):
    Vout = task.read()
    TempC = thermistor.thermistorTemp(Vout)
    print(round(TempC,1))
    datalogging.writefiledata(file, k*Ts, round(TempC,1))
    data.append(TempC)
    time.sleep(Ts)

# Terminate DAQ Device
task.stop
task.close()

# Close File
file.close()

# Plotting
t = np.arange(0,Tstop,Ts)
plt.plot(t,data, "-o")
plt.title('Temperature')
plt.xlabel('t [s]')
plt.ylabel('Temp [degC]')
plt.grid()
Tmin = 20; Tmax = 30
plt.axis([0, Tstop, Tmin, Tmax])
plt.show()
```

<https://www.halvorsen.blog>

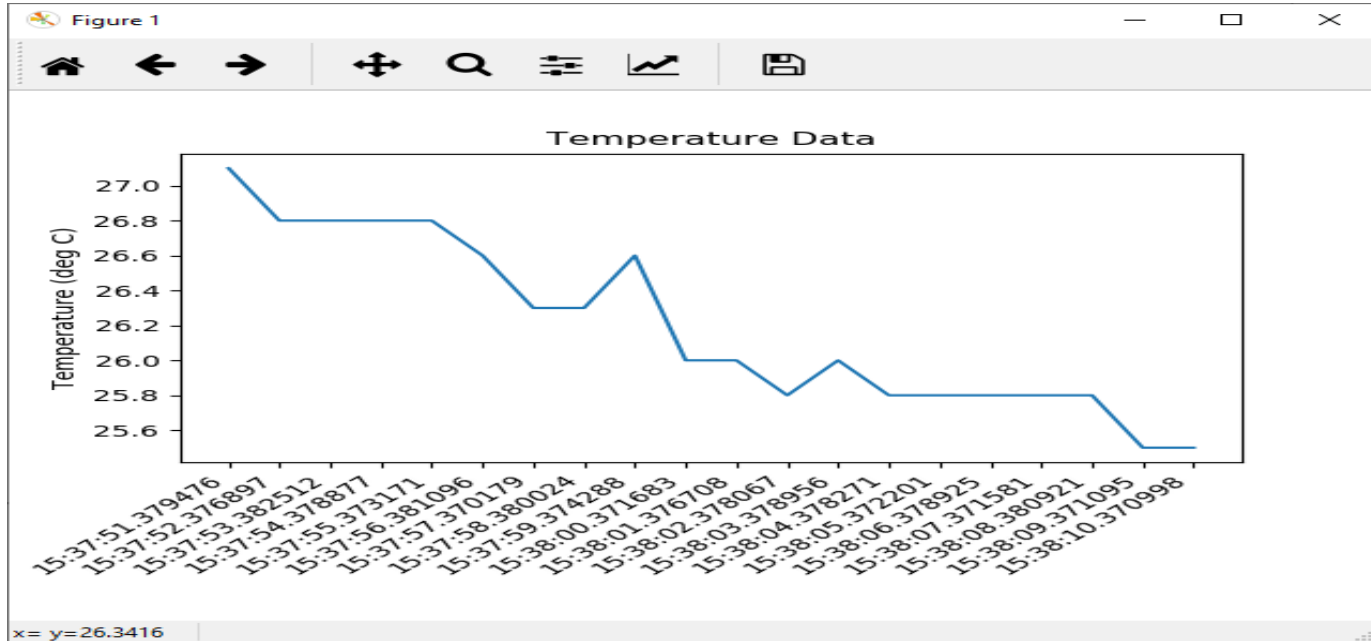


Real-Time Plotting of Data

Hans-Petter Halvorsen

Real-Time Plotting

Here in this Example we will read the value from the Temperature Sensor and Plot the Data in Real-Time



Python Code

```
import nidaqmx
import thermistor
import datetime as dt
import matplotlib.pyplot as plt
import matplotlib.animation as animation

Ts = 2 #Sampling Time in Seconds

# Initialize DAQ Device
from nidaqmx.constants import (
    TerminalConfiguration)

# Create figure for plotting
fig = plt.figure()
ax = fig.add_subplot(1, 1, 1)
xs = []
ys = []

# Initialize DAQ device
task = nidaqmx.Task()
task.ai_channels.add_ai_voltage_chan("Dev1/ai0",
    terminal_config=TerminalConfiguration.RSE)
task.start
```

```
# This function is called periodically from FuncAnimation
def readdaq(i, xs, ys):
    Vout = task.read()
    TempC = thermistor.thermistorTemp(Vout)

    # Add x and y to lists
    xs.append(dt.datetime.now().strftime('%H:%M:%S'))
    ys.append(TempC)

    # Limit x and y lists to 20 items
    xs = xs[-20:]; ys = ys[-20:]

    # Draw x and y lists
    ax.clear()
    ax.plot(xs, ys, "-o")

    # Format plot
    plt.xticks(rotation=45, ha='right')
    plt.subplots_adjust(bottom=0.30)
    plt.title('Temperature Data')
    plt.ylabel('Temperature (deg C)')

# Set up plot to call readdaq() function periodically
ani = animation.FuncAnimation(fig, readdaq,
    fargs=(xs, ys), interval=Ts*1000)

plt.show()
task.stop
```

<https://www.halvorsen.blog>

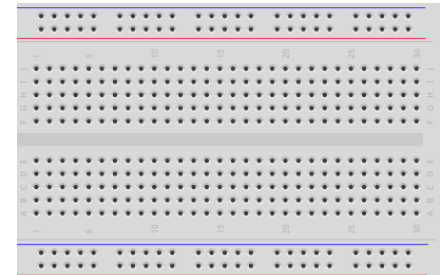
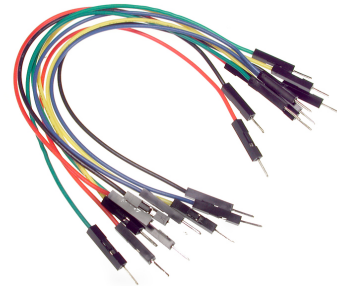
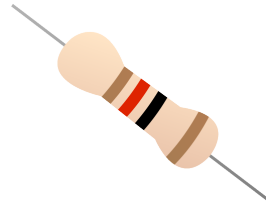


Temperature with Alarm

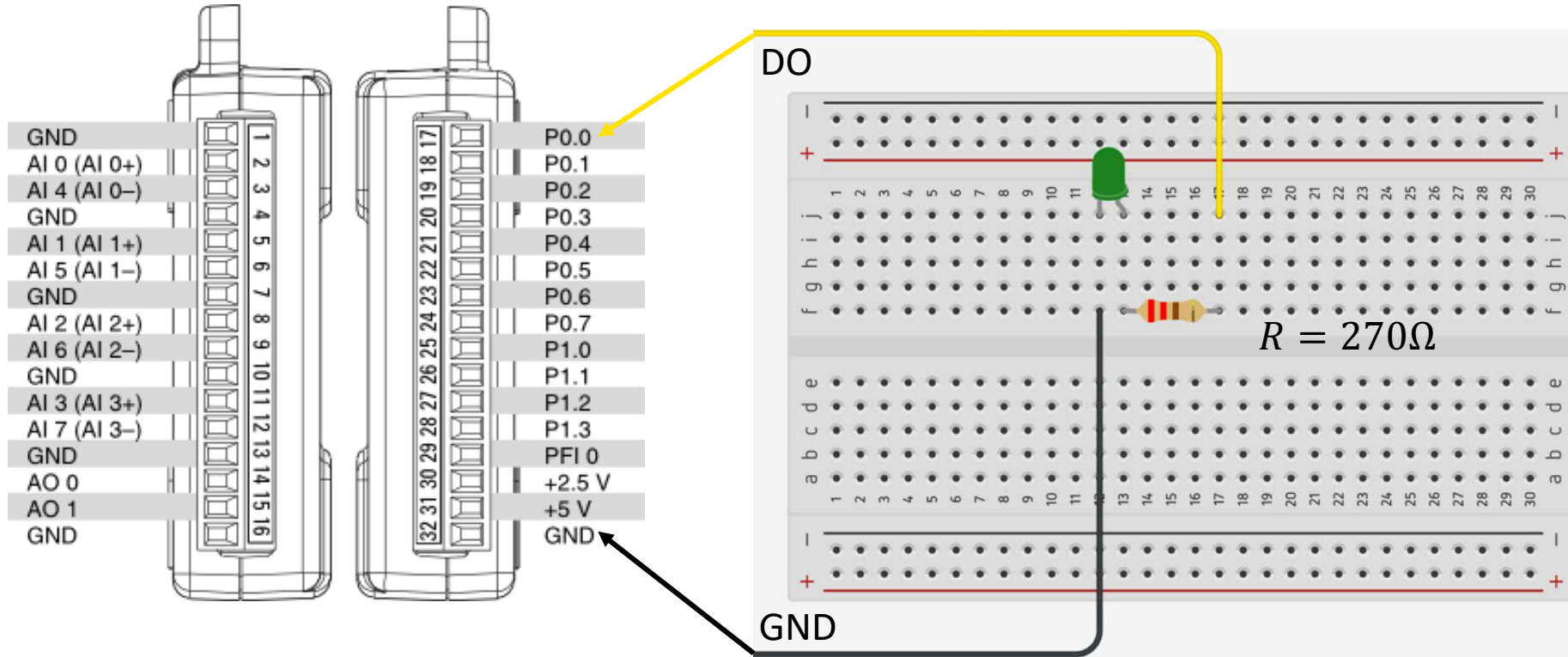
Hans-Petter Halvorsen

Necessary Equipment

- PC
- DAQ Module, e.g., USB-6008
- Breadboard
- Thermistor
- LED
- Resistor, $R = 270\Omega$
- Wires (Jumper Wires)



LED Wiring

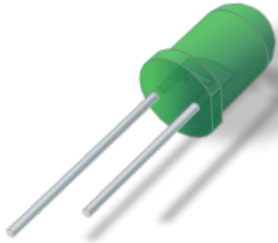


Python Code



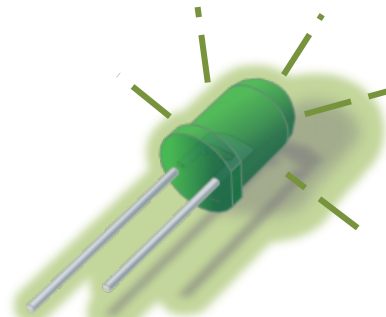
Temperature > Limit?

No



LED OFF

Yes



LED ON

```
import nidaqmx
import time
import thermistor

# Initialize DAQ Device
from nidaqmx.constants import (
    TerminalConfiguration)

# Initialize DAQ Device
task_ai = nidaqmx.Task()
task_ai.ai_channels.add_ai_voltage_chan("Dev1/ai0",
                                       terminal_config=TerminalConfiguration.RSE)
task_ai.start()

task_do = nidaqmx.Task()
task_do.do_channels.add_do_chan("Dev1/port0/line0")
task_do.start()

alarmlimit = 28 #degrees Celsius

Ts = 2
N = 10
# Start Logging
for k in range(N):
    Vout = task_ai.read()
    TempC = thermistor.thermistorTemp(Vout)
    print(round(TempC,1))

    if TempC >= alarmlimit:
        task_do.write(True)
        print("Alarm!")
    else:
        task_do.write(False)
        print("OK")

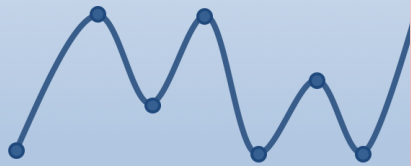
    time.sleep(Ts)

# Terminate DAQ Device
task_ai.stop; task_ai.close()
task_do.stop; task_do.close()
```

Additional Python Resources

Python Programming

Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Science and Engineering

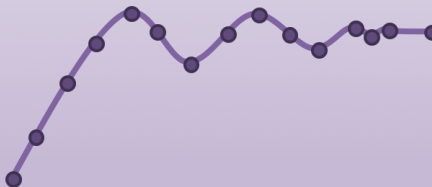
Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Control Engineering

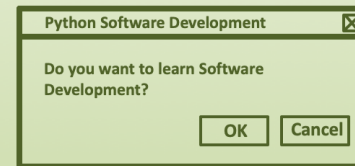
Hans-Petter Halvorsen



<https://www.halvorsen.blog>

Python for Software Development

Hans-Petter Halvorsen



<https://www.halvorsen.blog>

<https://www.halvorsen.blog/documents/programming/python/>

Hans-Petter Halvorsen

University of South-Eastern Norway

www.usn.no

E-mail: hans.p.halvorsen@usn.no

Web: <https://www.halvorsen.blog>

